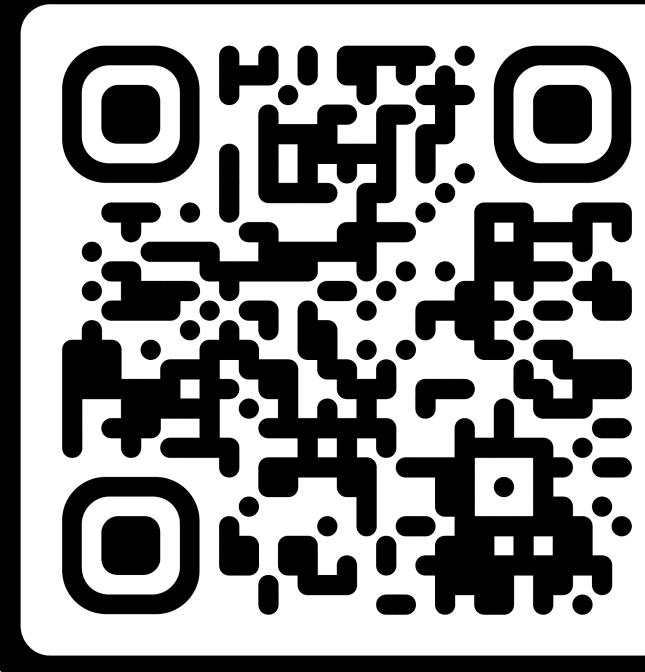


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## Introduction

Consider  $\mathcal{D} = \{x_i\}_{i=1}^n$  with  $x_i \in \mathbb{R}^d$  i.i.d. from an unknown distribution  $\pi_{\text{data}}$ .

**Goal.** Learn a generative mechanism whose output distribution  $\hat{\pi}$  is close to  $\pi_{\text{data}}$  (e.g., in Wasserstein distance  $\mathcal{W}_2$ ).

**Score-based Generative Models (SGMs).** Construct

- a *forward noising process* transporting  $\pi_{\text{data}}$  to a simple prior  $\pi_\infty$ ,
- a *backward denoising process* mapping noise samples back to data.

**Classical SGMs.** Starting from  $\vec{X}_0 \sim \pi_{\text{data}}$ , common forward processes include

$$\text{VP SDE: } d\vec{X}_t = -\vec{X}_t dt + \sqrt{2} dB_t,$$

$$\text{VE SDE: } d\vec{X}_t = \sqrt{2} dB_t,$$

$$\text{Flow matching: } \vec{X}_t = (1-t)\vec{X}_0 + tZ, \quad Z \sim \mathcal{N}(0, I_d) \perp \vec{X}_0, \quad t \in [0, 1].$$

**Kinetic SGMs (this work)** evolve in an extended position/velocity phase space.

## Framework

**Forward process.** Kinetic phase-space dynamics for  $\vec{U}_t = (\vec{X}_t, \vec{V}_t) \in \mathbb{R}^{2d}$ :

$$d\vec{U}_t = A\vec{U}_t dt + \Sigma dB_t, \quad \vec{U}_0 \sim \pi_{\text{data}} \otimes \pi_v, \quad (1)$$

with

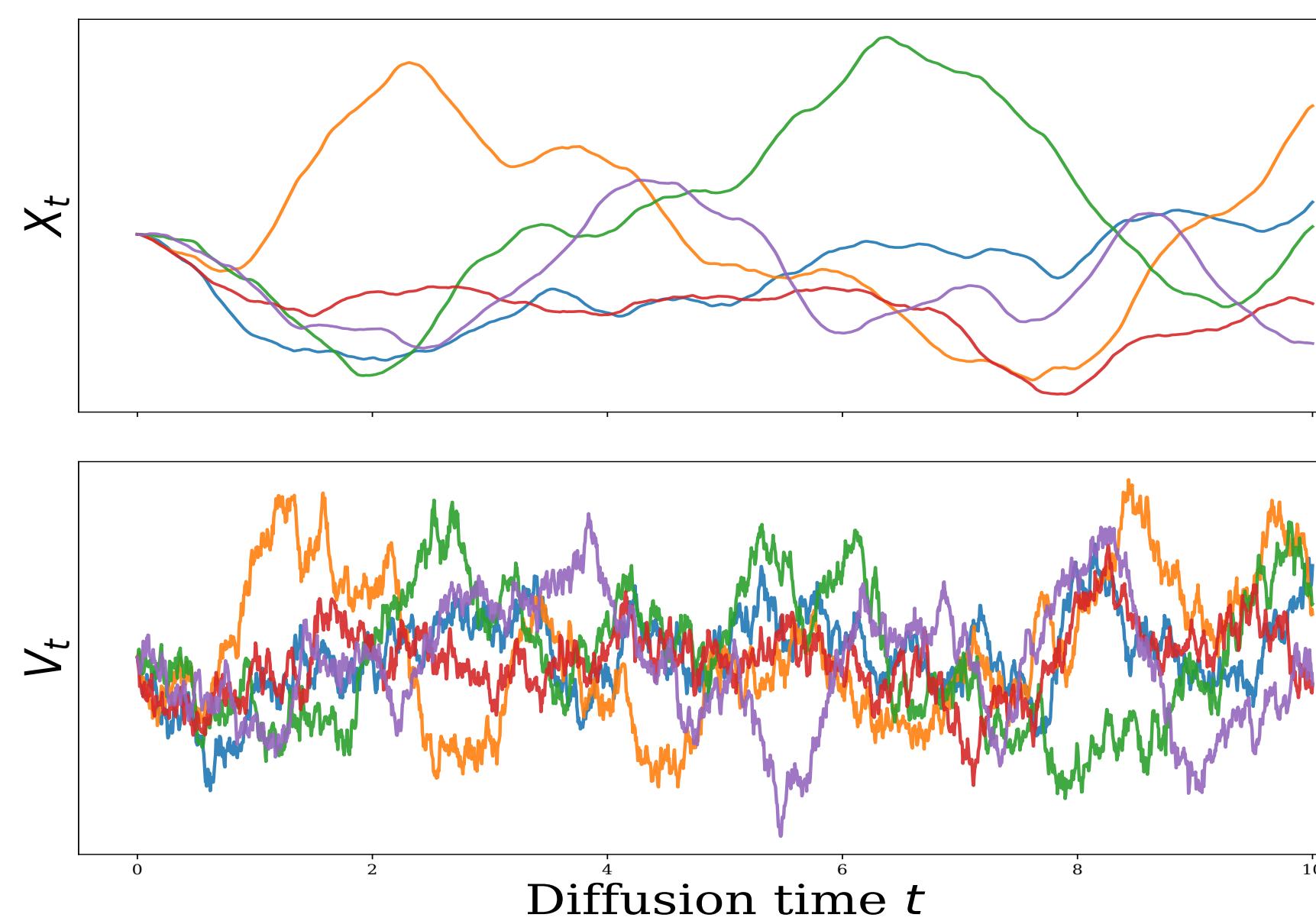
$$A = \begin{pmatrix} 0 & a^2 \\ -\mathbf{I}_d & -2a\mathbf{I}_d \end{pmatrix}, \quad \Sigma = \begin{pmatrix} 0 & 0 \\ 0 & \sigma\mathbf{I}_d \end{pmatrix}, \quad \pi_v = \mathcal{N}(0, v^2\mathbf{I}_d).$$

☞ *Hamiltonian-like coupling of  $(X, V)$ , with noise injected only in the velocity.*

**Backward process.** [1]  $(\vec{U}_t)_{t \in [0, T]} \xrightarrow{\mathcal{L}} (\vec{U}_{T-t})_{t \in [0, T]}$  follows

$$d\vec{U}_t = -A\vec{U}_t dt + \Sigma^2 \nabla \log p_{T-t}(\vec{U}_t) dt + \Sigma dB_t, \quad \vec{U}_0 \sim p_T, \quad (2)$$

with  $p_t$  the p.d.f. of (1). Let  $Q_t$  be the semigroup of (2), so that  $\pi_{\text{data}} = p_T Q_T$ .



## Prior work

- Empirical evidence that CLDs outperform standard SGMs in practice [2].
- KL convergence analyses of kinetic Langevin dynamics for the special case  $a = 1$ ,  $\sigma = 2$  [3, 4].
- **Gap:** no Wasserstein convergence guarantees are known for CLDs.

## SGM-CLDs in Practice

☞  $p_T$  is not accessible, but for large  $T$ , the process forgets its initialization.

$$p_T \approx \pi_\infty \sim \mathcal{N}(0, \Sigma_\infty).$$

■ **Mixing-time error:**  $\pi_{\text{data}} \approx \pi_\infty Q_T$

☞ Score function  $\nabla \log p_t$  is intractable but can be approximated by a deep neural network  $s_\theta$  via score matching.

■ **Approximation error:**  $\pi_{\text{data}} \approx \pi_\infty Q_T^\theta$

☞ Backward drift is **non-linear** and should be discretized into  $N$  finite steps.

■ **Discretization error:**  $\pi_{\text{data}} \approx \pi_\infty Q_{T,N}^\theta := \hat{\pi}_{\infty,N}^\theta$

Convergence results for SGMs rely on controlling each of the sources of error:

$$\begin{aligned} \mathcal{W}_2(\pi_{\text{data}}, \hat{\pi}_{\infty,N}^\theta) &\leq \underbrace{\mathcal{W}_2(\mathcal{L}(\vec{U}_T), \mathcal{L}(\vec{U}_N))}_{\text{Discretization}} + \underbrace{\mathcal{W}_2(\mathcal{L}(\vec{U}_N), \mathcal{L}(\vec{U}_{\infty,N}))}_{\text{Mixing}} \\ &\quad + \underbrace{\mathcal{W}_2(\mathcal{L}(\vec{U}_{\infty,N}), \mathcal{L}(\vec{U}_{\infty,N}^\theta))}_{\text{Score approximation}}. \end{aligned}$$

⚠ **Overcoming Hypoellipticity.** For non-kinetic SGMs, these terms are controlled by establishing a **contraction property in the Euclidean norm** via coupling arguments under **strong log-concavity** of  $p_t$  [5]. This condition no longer suffices for CLD: the dynamics are **hypoelliptic** (noise only in velocity).

## Solution 1: long-term Lipschitz regularity of the renormalized score

Let  $p_\infty$  be the invariant density of the forward CLD and  $\tilde{p}_t := p_t/p_\infty$ . The **renormalized backward dynamics** writes as

$$d\vec{U}_t = \tilde{A}\vec{U}_t dt + \Sigma^2 \nabla \log \tilde{p}_{T-t}(\vec{U}_t) dt + \Sigma dB_t,$$

where  $\tilde{A}$  is a negative definite matrix.

**Lipschitz continuity of renormalized score (exponential decay).** Under regularity assumptions on  $\pi_{\text{data}}$ , there exists  $C > 0$  such that, for all  $t \in (0, T]$ :

$$\|\nabla^2 \log \tilde{p}_t\| \leq C \left(1 + \frac{1}{\sqrt{t}}\right) e^{-2at} =: \tilde{L}_t.$$

**Norm contraction.**  $\tilde{L}_t$  is integrable and the backward flow contracts in a weighted norm, there exists  $\eta > 0$ :

$$\|\vec{U}_t^x - \vec{U}_t^y\|_{\mathfrak{M}} \leq C e^{-\eta t} \|\vec{U}_0^x - \vec{U}_0^y\|_{\mathfrak{M}}.$$

## Wasserstein Convergence Analysis of CLD

**Theorem:** Under mild regularity assumptions on  $\pi_{\text{data}}$ , there exist constants  $c_1, c_2, c_3 > 0$  such that

$$\mathcal{W}_2(\pi_{\text{data}}, \hat{\pi}_{\infty,N}^\theta) \leq c_1 e^{-c_2 T} + c_2 M + c_3 \sqrt{T/N},$$

with

$$\sup_{k \in \{0, \dots, N-1\}} \|\nabla \log \tilde{p}_{T-t_k}(\vec{U}_{t_k}^\theta) - s_\theta(T-t_k, \vec{U}_{t_k}^\theta)\|_{L_2} \leq M.$$

## Solution 2: restore ellipticity

Add a small amount of noise in the position coordinates:

$$\Sigma_\varepsilon = \begin{pmatrix} \varepsilon \mathbf{I}_d & 0 \\ 0 & \sigma \mathbf{I}_d \end{pmatrix}, \quad \varepsilon > 0.$$

**Consequences.**

► **Uniform ellipticity:** matrix Ornstein-Uhlenbeck process.

► **Standard analysis restored:** log-concave contraction in the Euclidean metric, enabling sharper quantitative bounds.

► **Practical effect:**  $\varepsilon$  controls sample-path smoothness.

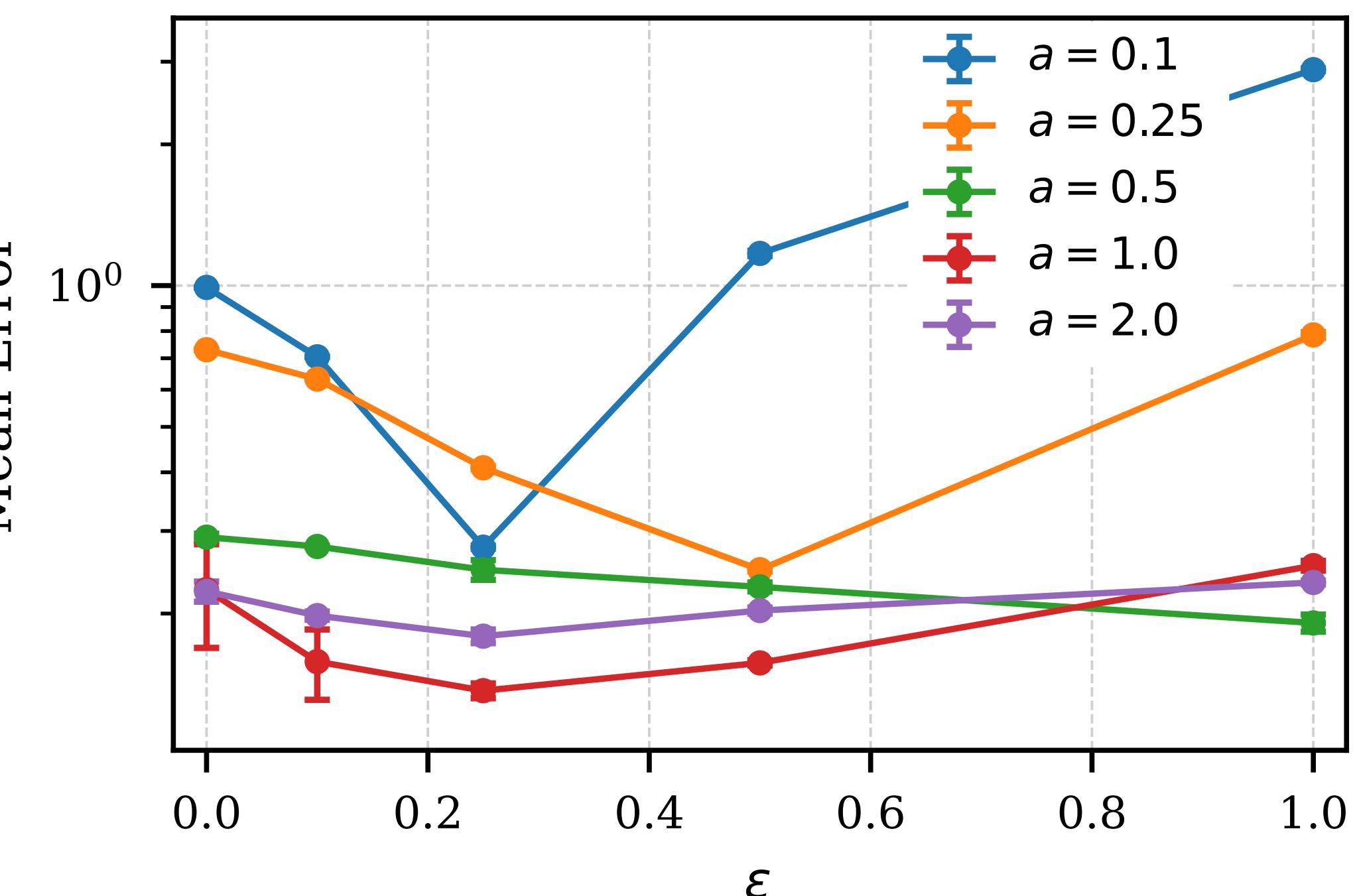


Figure: Mean sliced- $\mathcal{W}_2$  on the 100-dimensional **Funnel** distribution.

⇒ *Introducing a small regularization parameter  $\varepsilon$  improves generation quality.*

## Additional remarks.

- Even with a small  $\varepsilon > 0$ , **structure-preserving integrators** can further improve performance.
- **Trade-off:** training becomes more expensive, since the network must learn full gradients  $\nabla \log p_t(x, v)$  instead of velocity-only terms  $\nabla_v \log p_t(v)$ , effectively **doubling the dimension**.

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